

E. Spatial smoothing using MLM

→ chapter 13

• RWC consider this as a continuous-by-continuous interaction, or as bivariate smoothing. We'll consider their bivariate penalized spline approach in the next lecture(s).

• This lecture will discuss spatial analysis like you learned in your spatial class.

• The point: yet another class of models, developed independently, that can be expressed as a MLM at the price of leaving out some (not much?) of the older theory.

WARNING: I am not an expert in the area called "spatial statistics". I know a fair amount about so-called intrinsic CAR models.

IE 1/1

2/11/08

- Spatial stat is about measurements taken at locations and is distinctive in its concern about spatial correlation.
- Two common kinds of locations and data

① Geostatistical data

Location = x and y coordinates, interpreted literally as distances from an origin along axes

- interpolation between observed points is meaningful and often the main goal
- RWC's 2D splines can be used; I'll briefly show a more traditional approach.
(RWC Chapter 13.3 gives a different view.)

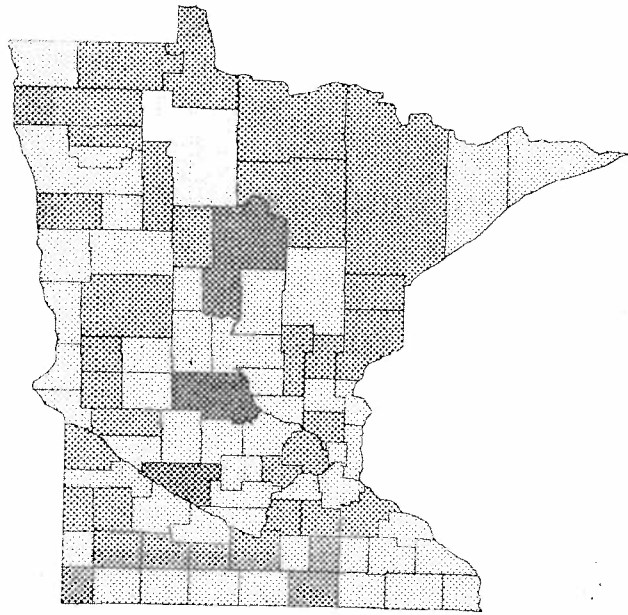
② Areal data

Location = a specific region on a map, with the measured variable being a total or average over the region.

Distance is not used explicitly; spatial "nearness" is specified by defining pairs of neighbors from among the regions on the map.

IE1/2 2/11/08 } Purpose: Smoothing & "borrowing strength"

Areal data continued: Two examples of regions (areas)

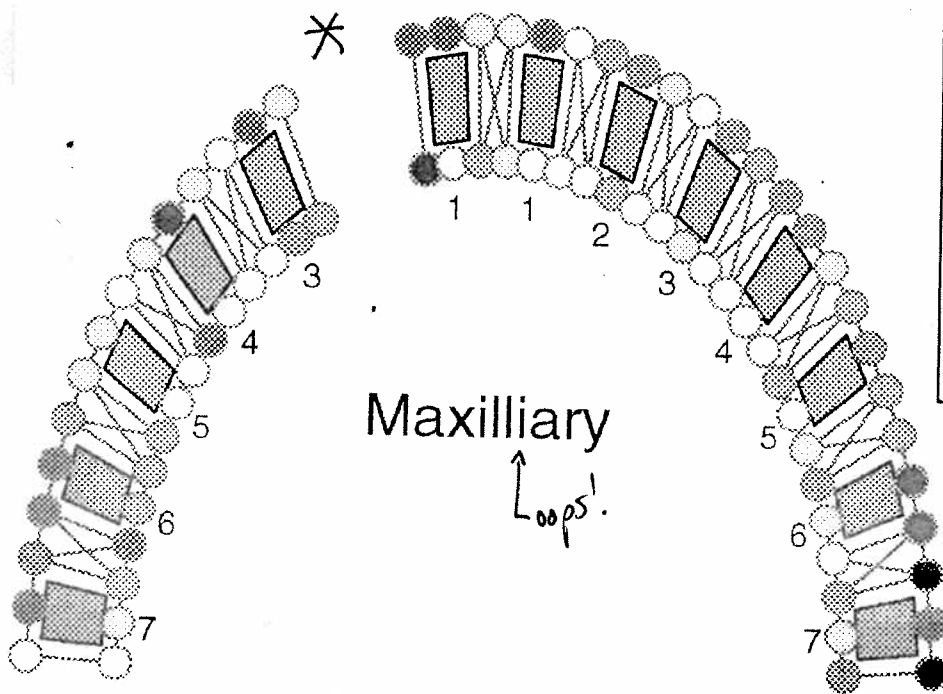


Common definition:

2 counties are a neighbor pair if they share a boundary

Periodontal data:

2 measurement sites "O" are a neighbor pair if they are touching or are joined by a line.



AL(mm)	
●	>5
●	5
●	4
●	3
●	2
○	0-1

This "map" has 2 "islands" because a tooth is missing at "*"

Fitting these models into MLM: Geostat

$$\text{MLM} \quad y = X\beta + Z u + \varepsilon$$

$n \times 1$ $n \times g$ $g \times 1$ $n \times 1$

① $\text{cov}(\varepsilon) = R$ captures spatial correlation

e.g., $R = [R_{ij}] \quad R_{ij} = \sigma_{\varepsilon}^2 I_n + \sigma_c^2 \exp(-d_{ij}/\theta)$

"nugget"

d_{ij} = distance between observations i, j

② $\text{cov}(\varepsilon) = \sigma_{\varepsilon}^2 I_n \quad Z = I_n \leftarrow g = n$

$\text{cov}(u)$ has a spatial structure

e.g., $G = [G_{ij}] \quad G_{ij} = \sigma_u^2 \exp(-d_{ij}/\theta)$

gives y the same marginal covariance as approach ①

Fitting areal models into MLM

Simplest case: $y = \delta + \varepsilon$
 $\varepsilon \sim N_n(0, \sigma_\varepsilon^2 I_n)$

δ has a CAR model/distribution/prior
(Note: other models exist, e.g. SAR)

The CAR model can be specified several ways

Pair wise differences (Besag 1974 [?])

$$f(\underline{\delta} | \tau^2) \propto \exp\left(-\frac{1}{2\tau^2} \sum_{i \sim j} (\delta_i - \delta_j)^2\right) \quad \begin{array}{l} "i \sim j" = "i \& \\ j \text{ are neighbors"} \end{array}$$

It is easy to show $f(\underline{\delta} | \tau^2) \propto (\tau^2)^{-\frac{(n-G)}{2}} \exp\left(-\frac{1}{2\tau^2} \underline{\delta}' Q \underline{\delta}\right)$

$G = \#$ of islands in the spatial map
 \leftarrow oops!
 $Q = (q_{ij})$: $q_{ii} =$ region i 's number of neighbors
 $q_{ij} = \begin{cases} -1 & \text{if } i \sim j \\ 0 & \text{otherwise.} \end{cases}$

- Q has G zero eigenvalues, one for each island.
- $\forall Q$, $\mathbf{1}_n$ is an eigenvector with zero eigenvalue.

Conditional mean and variance

$$E(\delta_i | \delta_{(-i)}) = \frac{1}{m_i} \sum_{j \sim i} \delta_j$$

$$m_i = \begin{cases} \# \text{ of neighbors} \\ \text{of region } i \end{cases}$$

$$\text{Var}(\delta_i | \delta_{(-i)}) = \tau^2 / m_i$$

This implies the same (singular) joint density of δ .

A more general specification for the CAR

$$\delta \sim N(0, \tau^2 (D - \rho C)^{-1})$$

- D is diagonal

- C has $c_{ii} = 0$, $c_{ij} = c_{ji} \neq 0$; $d_{ii} = \sum_{j=1}^n c_{ij}$

- $\rho \in [0, 1]$ describes spatial dependence (unguilty!)

- Reduces to our ICAR if $\rho = 1$ and

$$c_{ij} = \begin{cases} 1 & i \sim j \\ 0 & \text{otherwise} \end{cases}$$

- How to fit this into the MLM?

If $y = \delta + \varepsilon$, $\delta \sim \text{CAR}(\tau^2, Q)$

We can't write $\delta \sim N_n(0, \overset{\text{sops!}}{G^*})$ because the CAR (ICAR, actually) specifies a singular distribution: $G^{*-1} = \frac{1}{\tau^2} Q$ has zero eigenvalues.

- A little cleverness is needed

$Q = V D V'$ for V orthogonal, D diagonal

$$D = \begin{bmatrix} D_1 & | & 0 \\ \hline 0 & | & 0_{6 \times 6} \end{bmatrix}$$

D_1 is $(N-6) \times (N-6)$ diagonal, with $D_1 = \text{diag}(d_1, \dots, d_{N-6})$ and $d_j > 0$

$V = [V_1 | V_2]$ V_1 has $N-6$ columns, V_2 has 6

- So $\delta \sim \text{CAR}(\tau^2, Q)$ implies

$u = V_1' \delta \sim N_{N-6}(0, \tau^2 D_1^{-1})$, $\beta = V_2' \delta$ has a flat prior, i.e., it's a fixed effect.

$\text{col}(V_2)$ includes I_n ; more generally

IE 1/7 2/11/08

$\text{col}(V_2)$ fits the island means

$$\delta \sim \text{CAR}(\tau^2, Q) \quad Q = VDV', \quad V = \begin{bmatrix} V_1 & | & V_2 \\ \hline N-G & & G \end{bmatrix}$$

$$u = V_1' \delta \sim N_{N-G}(0, \tau^2 D_1^{-1})$$

$$D = \begin{bmatrix} D_1 & | & 0 \\ \hline 0 & | & 0_{G \times G} \end{bmatrix}$$

$\beta = V_2' \delta$ is fixed effects (G of them)

$$\text{So } y = \delta + \varepsilon$$

$$= VV' \delta + \varepsilon$$

$$= V \begin{pmatrix} V_1' \delta \\ V_2' \delta \end{pmatrix} + \varepsilon$$

$$= V \begin{pmatrix} u \\ \beta \end{pmatrix} + \varepsilon$$

$$= \underset{\substack{\uparrow \\ G \times 1}}{V_2} \beta + \underset{\substack{\uparrow \\ (N-G) \times 1}}{V_1} u + \varepsilon$$

$$\text{cov}(\varepsilon) = R = \sigma_\varepsilon^2 I_n$$

$$\text{cov}(u) = \cancel{X} = \tau^2 D_1^{-1}$$

↑
Loops!

- V_2 is the main effect for island means
 - if $G = 1$ island, $V_2 = 1_n$ is an intercept.

- This is easily extended to include fixed effects besides the island means.
- If X 's columns are the other fixed effects (without an intercept), then the MLM

expression is

$$y = V_2 \underset{\substack{\text{intercepts} \\ \downarrow \\ (\mathbf{I})}}{\beta} + X \underset{\substack{\text{predictors} \\ \downarrow \\ (\mathbf{P})}}{\beta} + V_1 u + \varepsilon$$

$$\text{cov}(u) = G^* = \tau^2 D_i^{-1}$$

$$\text{cov}(\varepsilon) = R = \sigma_\varepsilon^2 I_n$$

What are the columns of V_1 ?

How do we interpret them?

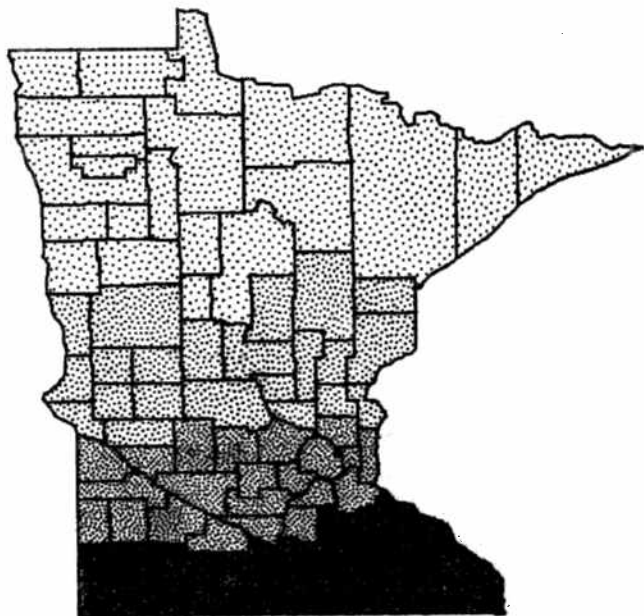
We have some intuition based on examples.

Counties of Minnesota

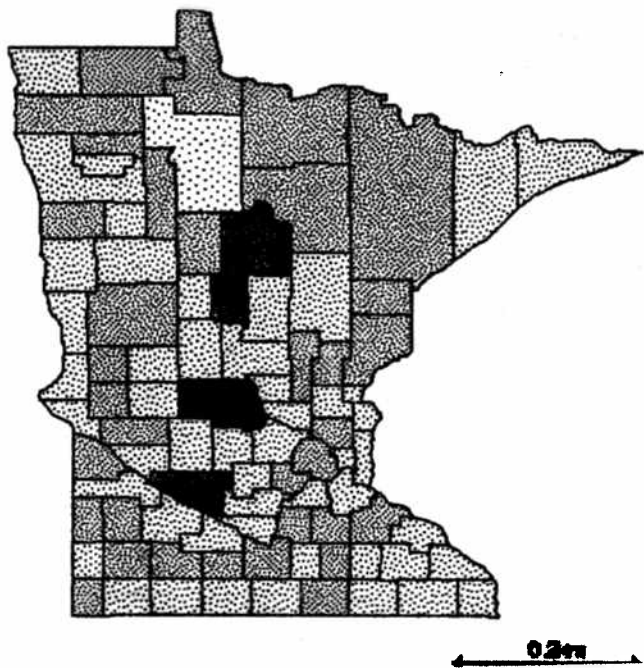
Recall

$$Q = \begin{bmatrix} V_1 & V_2 \end{bmatrix} \begin{bmatrix} D_1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V_1^T \\ V_2^T \end{bmatrix}$$

Prior precision is $\frac{1}{\tau^2} Q$



- Column of V_1 corresponding to smallest $d_i > 0$ i.e., weakest prior constraint



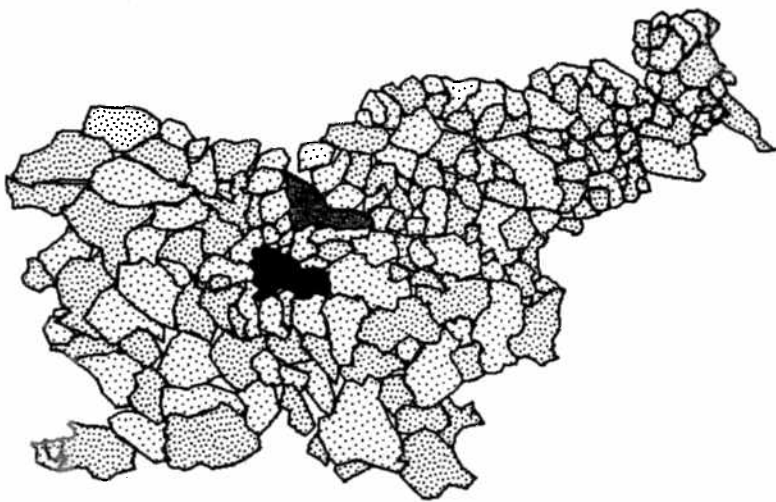
Column of V_1 corresponding to largest $d_i > 0$, i.e., strongest prior constraint.

Municipalities of Slovenia



$$V_1 u \text{ is RE}$$
$$\text{cov}(u) = \tau^2 D_1^{-1}$$

Column of V_1
corresponding to
smallest $d_i > 0$,
i.e., weakest prior
constraint



Column of V_1
corresponding to
largest $d_i > 0$,
i.e., strongest
prior
constraint.

Periodontal Data

Smallest $d_i > 0$ (weakest prior constraint)



midddling $d_i > 0$ (moderate prior constraint)



largest $d_i > 0$ (strongest prior constraint)



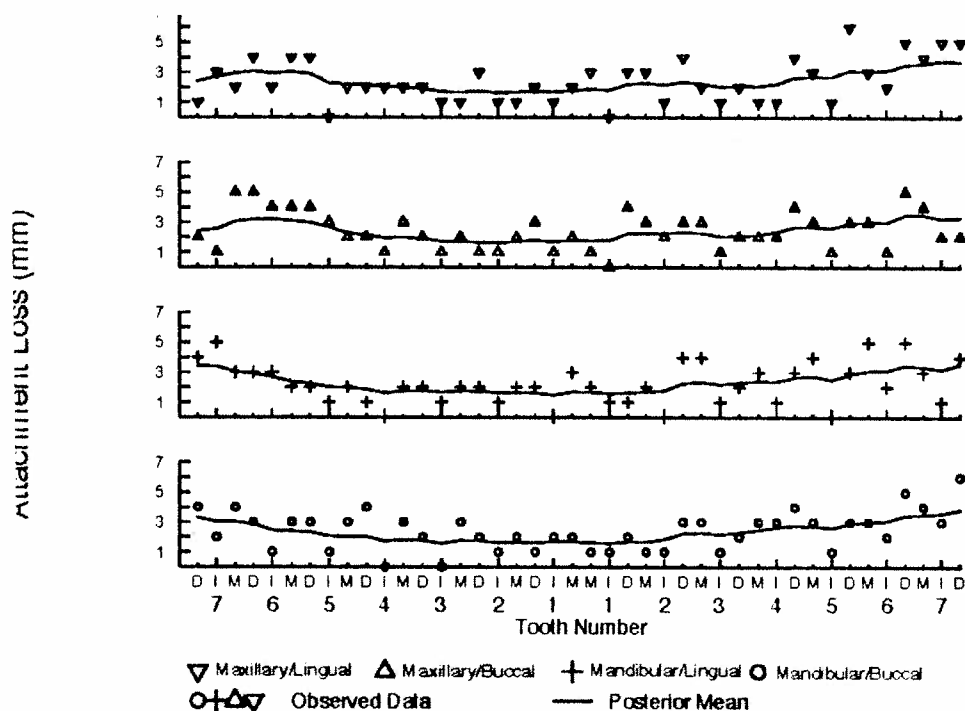
Tentative generalization:

- low-frequency (large-scale) contrasts are smoothed least
- high-frequency (small-scale) contrasts are smoothed most, i.e. are largely pushed into error.

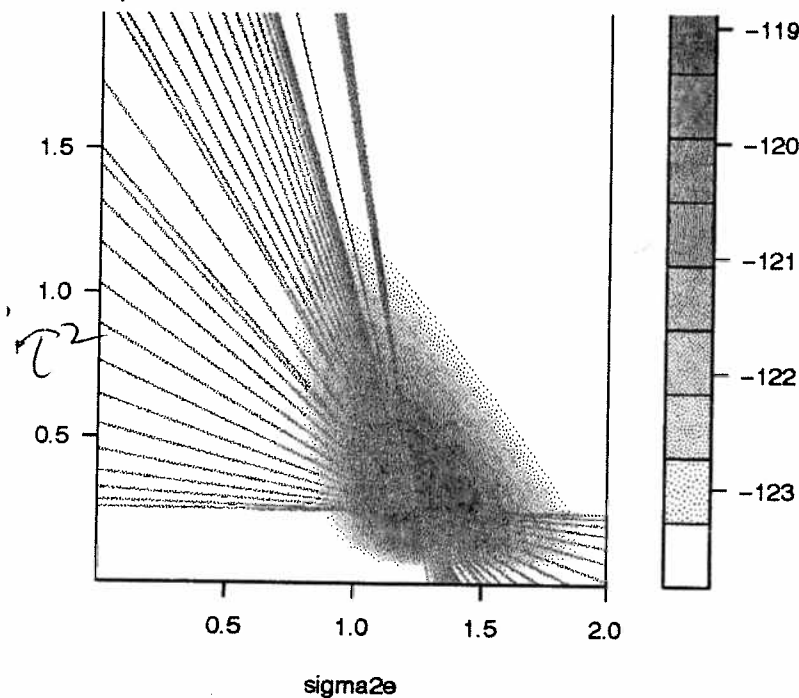
Thesis topic: Demonstrate this in some generality.

Example: Attachment loss data (Reich & Hodges 200)

Data and simplest CAR fit



Marginal posterior of σ_ϵ^2 and σ_u^2



The lines correspond to distinct positive eigenvalues of $Q(d_i)$ - more later!

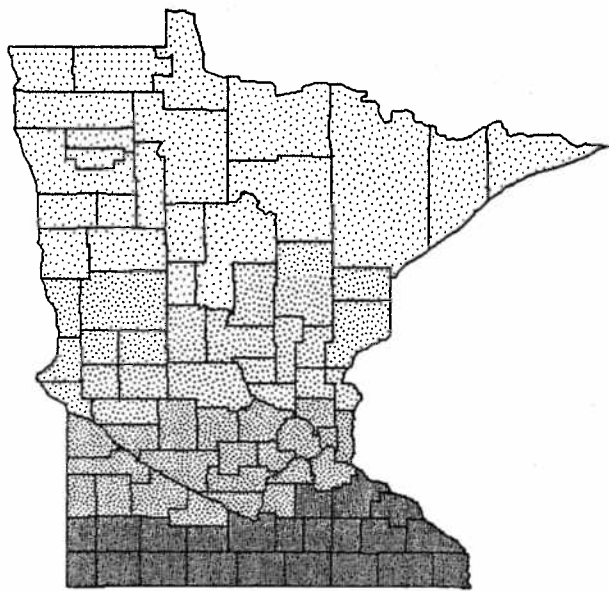
IE 1/14 2/13/08

CAR Models/Priors are modular also.

Example: Using CAR in SANOVA to smooth a spatial effect (Zhang, Hodges, Banerjee '07)

3-cancer dataset: For each of MN's 87 counties, we have incidence of 3 cancers: lung, larynx, esophagus

• This can be viewed as a 3×87 ANOVA, in which we smooth counties using a CAR model.



Note: only one island, so only one zero eigenvalue in Q , corresponding to $V_2 = \frac{1}{\sqrt{87}} \mathbf{1}_{87}$

To fit this into SANOVA, we need:

- The same re-parametrization trick for the CAR model
 - Here $V_2 = V^{(-)}$
- a 3×2 matrix H_{CA} with orthonormal columns, describing 2 contrasts in the cancers.

In the MLM framework $y = X\beta + Zu + \varepsilon$:

Fixed effects:

Grand mean &

Cancer main effect

$$X = \left[\begin{array}{c|c} \frac{1}{\sqrt{3 \times 87}} \mathbf{1}_{3 \times 87} & \frac{1}{\sqrt{87}} \mathbf{1}_{87} \otimes H_{CA} \end{array} \right]$$

where $A \otimes B = [a_{ij} B]$

Random effects

county main effect

County-by-cancer interaction

1st column

2nd column

$$Z = \left[\begin{array}{c|c|c} V^{(-)} \otimes \frac{1}{\sqrt{3}} \mathbf{1}_3 & V^{(-)} \otimes H_{CA}^{(1)} & V^{(+)} \otimes H_{CA}^{(2)} \end{array} \right]$$

$u_0 \ 86 \times 1$ $u_1 \ 86 \times 1$ $u_2 \ 86 \times 1$

$\text{Cov}(u_j) \ T_0^2 D_1^{-1}$

$T_1^2 D_1^{-1}$

$T_2^2 D_1^{-1}$

IE 1/17 2/13/08

• This is a restriction of the multivariate CAR (MCAR) model

• MCAR is specified by the same Q describing spatial neighbor pairs

AND $\Sigma =$ covariance of cancers in a county

• If $\Sigma = \Phi \Delta \Phi'$ is the spectral decomposition of Σ

the SANOVA presumes $\Phi = \left[\frac{1}{\sqrt{3}} \mathbf{1}_3 \mid H_{CA} \right]$ is known.

• Z, H, & B shows that this is competitive with MCAR even when $\left[\frac{1}{\sqrt{3}} \mathbf{1}_3 \mid H_{CA} \right]$ is "wrong"

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