

Causal machine learning

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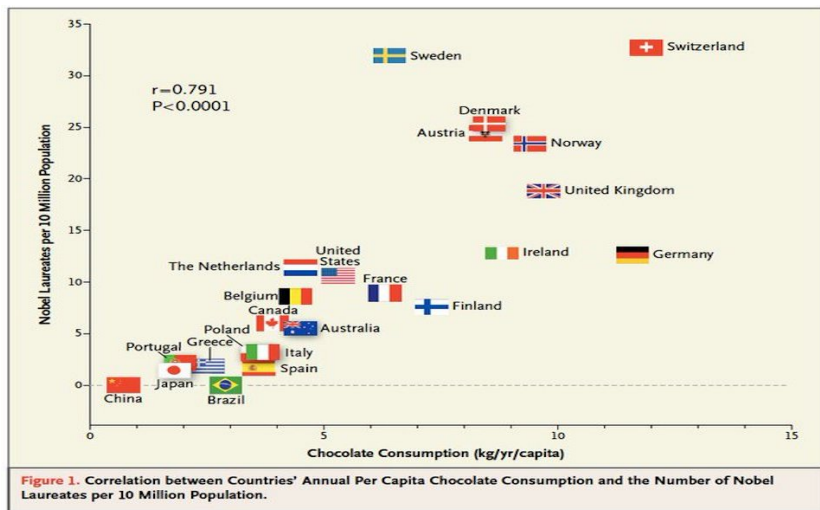
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Outline

- ▶ Causal inference in the presence of hidden confounding
 - ▶ Instrumental variable (IV) regression: 2SLS
 - ▶ Mendelian randomization (MR)
 - ▶ Network deconvolution (ND)
 - ▶ DeepIV
- ▶ Causal inference without confounding
 - ▶ Counterfactual model
 - ▶ Standard approaches
 - ▶ New (ML) approaches
 - ▶ Causal trees and forests

Chocolate consumption vs Nobel prize winning: Messerli 2012, NEJM



Chocolate consumption vs Nobel prize winning: flavanoids?

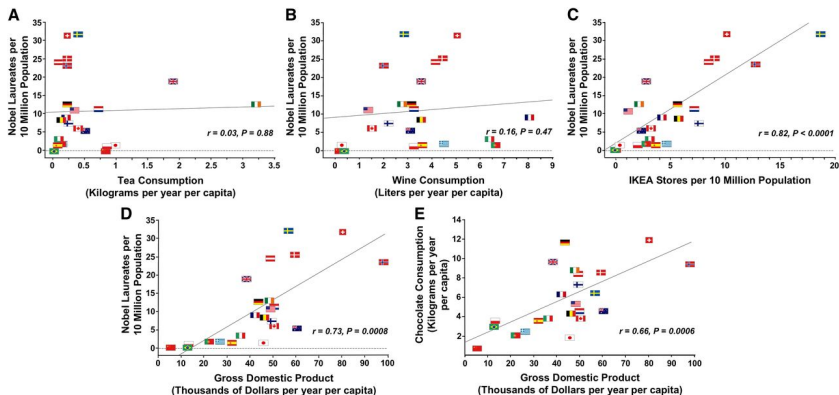


Figure: Fig 1 in Maura et al 2013, *J Nutrition*.

Introduction: motivation

Adam, D. (2019). The gene-based hack that is revolutionizing epidemiology: Mendelian randomization offers a simple way to distinguish causation from correlation. But are scientists overusing it? *Nature*, 576:196-199.

- ▶ Limitations of epi/observational/association studies \implies
- ▶ Failures of multiple \$100-million trials!
- ▶ Causal inference!
- ▶ MR: causal inf with observational data
- ▶ Easy to use: wide availability of GWAS summary data
- ▶ Magic? No! Strong modeling assumptions...
- ▶ Boef (2015, *IJE*): 178 published, $< 1/2$ "adequately discussed these assumptions"
- ▶ *"Statistical tools for epidemiology are improving. And although Mendelian randomization does not always offer perfect clarity, it might, at least, point researchers in the right direction."*

Introduction: IV reg and MR

- ▶ MR: a special application of instrumental variable (IV) reg.
2S-2SLS
using (indep) genetic variants/SNPs as IVs
GWAS summary data
Bowden, Burgess, Davey Smith,;
- ▶ IV reg for causal inference
Angrist, Imbens won a half of the 2021 Nobel Prize in
Economics:
Angrist, J.D. and G.W. Imbens (1995). “Two-stage least
squares estimation of average causal effect in models with
variable treatment intensity.” *JASA*, 90(430): 431-442.
Angrist, J.D., G.W. Imbens, and D.B. Rubin (1996).
“Identification of causal effects using instrumental variables.”
JASA, 91: 444-472.
Imbens, G.W. and J.D. Angrist (1994). “Identification and
estimation of local average treatment effects.” *Econometrica*,
61: 467-476.

IV reg: Basic Idea

- ▶ True **causal** model:

$$X = Z\beta_X + U\beta_{XU} + \epsilon_X^*, \quad Y = X\theta + U\beta_{YU} + \epsilon_Y^*.$$

- ▶ θ : parameter of interest; e.g., $H_0: \theta = 0$.
- ▶ Key challenge: **hidden** confounder U
 $\implies \hat{\theta}$ **biased** in $Y \sim X$.

Why?

- ▶ 2-Stage Least Square (2SLS): under 3 valid IV assumptions,

$$E(Y|Z) = \theta E(X|Z) \implies$$

Stage 1: $\hat{X} = Z\hat{\beta}_X$,

Stage 2: $Y = \hat{X}\theta + \epsilon_Y$.

Consistent and AN (but low efficiency)!

- ▶ a Key feature: 2-sample 2SLS,
can infer θ with two independent samples $\{(Z_i, X_i)\}$'s and $\{(Z_i, Y_i)\}$'s!

MR: Basic Idea

- ▶ MR: consider one IV,

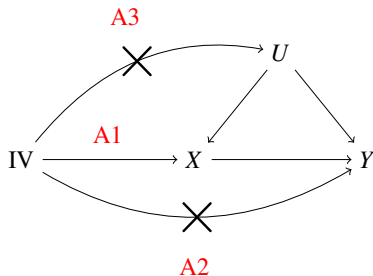
$$X = Z_i\beta_{X_i} + \epsilon_X, \quad Y = X\theta + \epsilon_Y^{**} = Z_i\beta_{Y_i} + \epsilon_Y$$

Key: $\beta_{Y_i} = \beta_{X_i}\theta$

- ▶ MR: under the 3 valid IV assumptions, $\hat{\theta} = \hat{\beta}_{Y_i}/\hat{\beta}_{X_i}$ unbiased, consistent, AN, ...
- ▶ $\hat{\beta}_{Y_i}, \hat{\beta}_{X_i}$ (and $\hat{\sigma}_{Y_i}^2, \hat{\sigma}_{X_i}^2$) directly available from two indep GWAS summary datasets.
- ▶ If multiple indept IVs, combine by meta-analysis: IVW(FE), ...

Assumptions

A



B

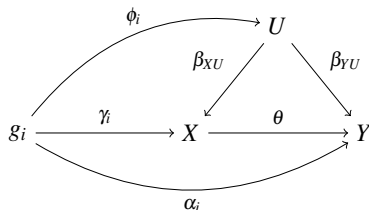
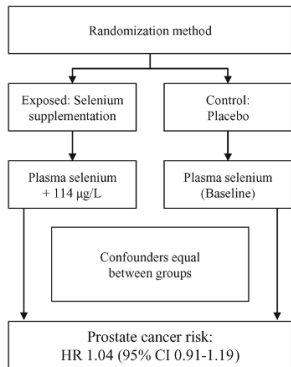


Figure: (A) Three assumptions for valid IVs. (B) Our causal model.

- ▶ Violation of A2: uncorrelated pleiotropy; $\beta_{X_i} = \gamma_i$, α_i uncor.
- ▶ Violation of A3: correlated pleiotropy;
 $\beta_{X_i} = \gamma_i + \phi_i \beta_{XU}$, $\alpha_i + \phi_i \beta_{YU}$ correlated \implies
violation of InSIDE required by MR-Egger, IVW(RE), RAPS
(treating α_i random).

MR vs RCT

Randomized Controlled Trial (SELECT)



Mendelian Randomization

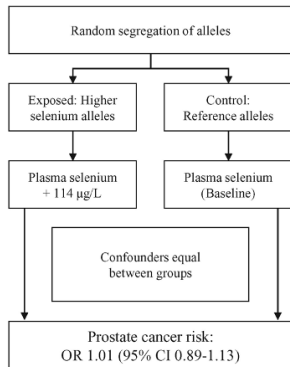


Figure: Yarmolinsky, James, et al. "Circulating selenium and prostate cancer risk: a Mendelian randomization analysis." *JNCI: Journal of the National Cancer Institute* 110.9 (2018): 1035-1038.

UVMR-cML (Xue, Shen and Pan (2021, AJHG))

- ▶ Key: relax Assumptions (A1), A2 & A3.
- ▶ A more general (true causal) model:

$$\beta_{X_i} = \gamma_i + \beta_{XU} \cdot \phi_i,$$

$$\beta_{Y_i} = \theta \cdot (\gamma_i + \beta_{XU} \cdot \phi_i) + \alpha_i + \beta_{YU} \cdot \phi_i = \theta \cdot \beta_{X_i} + r_i,$$

- ▶ From the GWAS data: $\hat{\beta}_{X_i} \sim N(\beta_{X_i}, \hat{\sigma}_{X_i}^2)$ and $\hat{\beta}_{Y_i} \sim N(\beta_{Y_i}, \hat{\sigma}_{Y_i}^2)$ for $i = 1, \dots, m$. All indep
- ▶ Log-likelihood:

$$L = -\frac{1}{2} \sum_{i=1}^m \left(\frac{(\hat{\beta}_{X_i} - \beta_{X_i})^2}{\hat{\sigma}_{X_i}^2} + \frac{(\hat{\beta}_{Y_i} - \theta \cdot \beta_{X_i} - r_i)^2}{\hat{\sigma}_{Y_i}^2} \right),$$

- ▶ Constrained maximum likelihood (cML):

$$\max L \text{ subject to } \sum_{i=1}^m I(r_i \neq 0) = K.$$

- ▶ Try $K = 0, 1, 2, \dots, m - 2$, then use BIC to select \hat{K} .
- ▶ A sequential algorithm: fast but ...

Theory

- ▶ Assumption 1: (Plurality valid condition.) Suppose that B_0 is the index set of the true valid IVs with $K_0 = |B_0|$. For any $B \subseteq \{1, \dots, m\}$ and $|B| = K_0$, if $B \neq B_0$, then the K_0 ratios $\{\beta_{Y_i}/\beta_{X_i}, i \in B\}$ are not all equal.
- ▶ Note: valid IVs: $\beta_{Y_i}/\beta_{X_i} = \theta$;
invalid IVs: $\beta_{Y_i}/\beta_{X_i} = \theta + r_i/\beta_{X_i} \neq \theta$.
- ▶ Assumption 2: (Orders of the variances and sample sizes.)
There exist positive constants l_X, l_Y, l_N and u_X, u_Y, u_N such that we have $l_X/N_1 \leq \hat{\sigma}_{X_i}^2 \leq u_X/N_1$, $l_Y/N_2 \leq \hat{\sigma}_{Y_i}^2 \leq u_Y/N_2$, and $l_N \cdot N_2 \leq N_1 \leq u_N \cdot N_2$ for $i = 1, \dots, m$.
- ▶ Note: usually satisfied, e.g. with LSE or MLE.

Theory

- ▶ Theorem 1: (Selection consistency.) With Assumptions 1 and 2 satisfied, if $K_0 \in \mathcal{K}$, we have $P(\hat{K} = K_0) \rightarrow 1$ and $P(\hat{B}_{\hat{K}} = B_0) \rightarrow 1$ as $N_1, N_2 \rightarrow \infty$.
- ▶ Theorem 2. (Consistency and AN.) With Assumptions 1 and 2 (and some regularity conditions), the cMLE $\hat{\theta}$ is consistent and asymptotically normal.
Note: similar to the theory in RAPS (Zhao et al 2020, AoS). Only valid IVs are used.
- ▶ Allowing the presence of weak IVs (i.e. A1 violated). similar to RAPS.
- ▶ Theorem 3. (DP/bootstrap is consistent.)

Finite-sample adjustments

- ▶ Model averaging (MA) (Buckland et al 1997, *B'cs*):

$$w_K^0 = \exp(-\text{BIC}(K)/2), \quad w_K = w_K^0 / \sum_{K \in \mathcal{K}} w_K^0,$$

$$\hat{\theta}_w = \sum_{K \in \mathcal{K}} w_K \cdot \hat{\theta}(K), \quad \text{SE}(\hat{\theta}_w) = \dots$$

- ▶ Data perturbation (DP): or, parametric bootstrap,
 $\hat{\beta}_{X_i}^{(t)} \sim N(\hat{\beta}_{X_i}, \hat{\sigma}_{X_i}^2)$ and $\hat{\beta}_{Y_i}^{(t)} \sim N(\hat{\beta}_{Y_i}, \hat{\sigma}_{Y_i}^2)$ for $i = 1, \dots, m$
obtain $\hat{\theta}^{(t)}(K)$ for $t = 1, 2, \dots, T$.

$$\hat{\theta}_{DP}(K) = \frac{\sum_{t=1}^T \hat{\theta}^{(t)}(K)}{T}, \quad \text{SE}(\hat{\theta}_{DP}(K)) = \text{SD}(\{\hat{\theta}^{(t)}(K)\}).$$

then apply MA (optional):

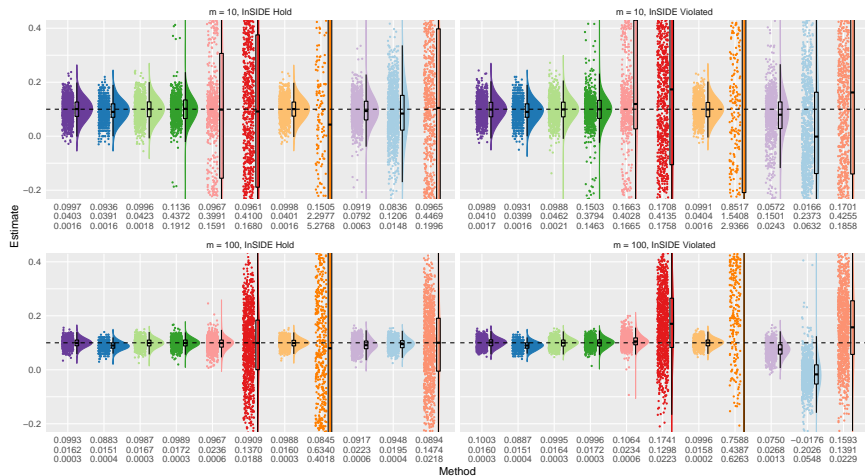
Bagging (Breiman 1996 *ML*; Efron 2014 *JASA*).

Simulations

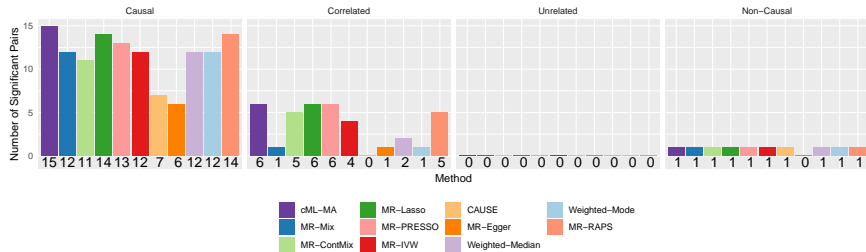
Compared with most state-of-the-art MR methods;
As expected, ...

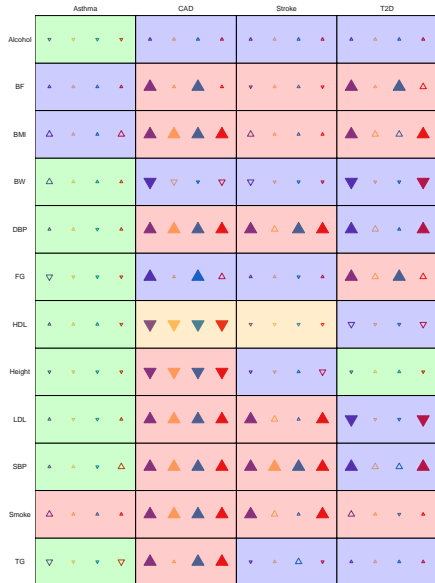
Simulation results:

$\theta = 0.1$, $n = 50000$, 60% Invalid



Applications:





Extensions/alternatives

- ▶ UVMR-cML-C: allowing overlapping samples (Lin, Xue and Pan 2023, PLOS Genet);
- ▶ MVMR-cML: allowing multiple exposures (Lin, Xue and Pan 2023, AJHG)
- ▶ Next: apply UVMR-cML-C and ND to infer (general) causal networks.
allowing cycles; data from different and possibly overlapping samples.
- ▶ A limitation: assuming the causal direction is known.
bi-directional MR
- ▶ Steiger's method (Hemani et al 2017, PLoS Genet):
Lemma. If $Z \rightarrow X \rightarrow Y$ and no hidden confounders, then $\text{corr}(Z, X) > \text{corr}(Z, Y)$.
With hidden confounders, it may not always hold;
Only working for one IV.
- ▶ Xue & Pan (2020, PLoS Genet): extending to multiple IVs.
- ▶ Xue & Pan (2022, PLoS Genet): Bi-directional CD-cML (and MR-cML).

Network deconvolution (ND)

- ▶ Feizi et al (2013, Nat Biotechnol.)
- ▶ Q: given a total-causal-effect graph G_t , how to estimate the direct-causal-effect graph G_d ?



$$G_t = G_d + G_d^2 + G_d^3 + \dots = G_d(I + G_d + G_d^2 + G_d^3 + \dots) = G_d(I - G_d)^{-1}$$

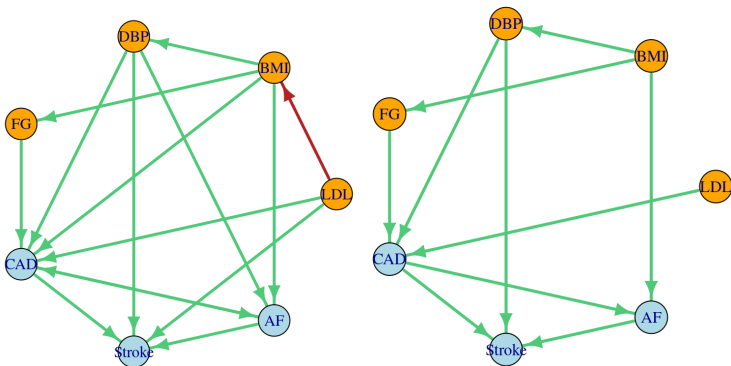
if $\rho(G_d) < 1$.

Hence, $G_d = G_t(I + G_t)^{-1}$.

- ▶ MR-cMLgraph (Lin, Xue and Pan, 2023, *PLOS Genet*): use MR-cML to construct \hat{G}_t , then use ND to obtain $\hat{G}_d = \hat{G}_t(I + \hat{G}_t)^{-1}$.
- ▶ Theory: $\text{vec}(\hat{G}_t)$ and $\text{vec}(\hat{G}_d)$ are consistent and AN.
- ▶ Can use data perturbation for inference.

Application: BMI might be a 'minor' risk factor for CAD,
but an indep one for AF

Figure: **Total (left) and direct (right) causal graphs**



ND: continued

- ▶ Derivation is for a directed graph; how about for an undirected graph?
- ▶ Let Σ be an invertible correlation matrix among a set of variables of interest. If $G_t = \Sigma - I$, then $G_d = I - \Omega$, where $\Omega = \Sigma^{-1}$ is the precision matrix.
Alipanahi and Frey (2013, Nature Biotechnol).
- ▶ Lior Pachter. The network nonsense of manolis kellis, February 2014. <https://liorpachter.wordpress.com/2014/02/11/the-network-nonsense-of-manolis-kellis/>.

DeepIV

- ▶ True model:

$$X = Z\alpha + U + \epsilon_X, \quad Y = g(X) + U + \epsilon_Y$$

- ▶ Again fitting $Y \sim X$ leads to biased estimate of $g(\cdot)$ due to hidden confounding!
- ▶ $E(Y|Z) = E[g(X)|Z]$.
- ▶ DeepIV (Hartford et al 2017, ICML): use a FNN $g_\theta(\cdot)$,

$$\hat{\theta} = \arg \min_{\theta} \sum_{i=1}^n [Y_i - \int g_\theta(x) dF(x|Z_i)]^2 + P(\theta; \lambda),$$

- ▶ Slow: need to use MC sampling,
 $\int g_\theta(x) dF(x|Z_i) \approx \sum_{j=1}^M g_\theta(X_{ij}), \quad X_{ij} \sim \hat{F}(x|Z_i).$
- ▶ Unstable: ill-posed inverse problem; Fredholm integral equation of the first kind (Newey 2013, Am Econ Rev).

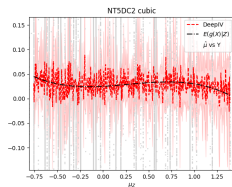
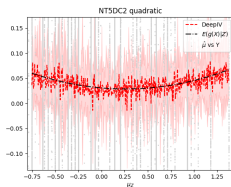
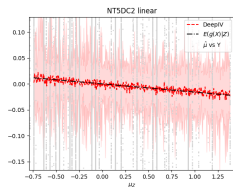
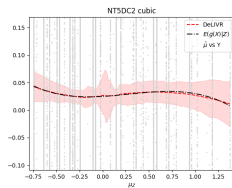
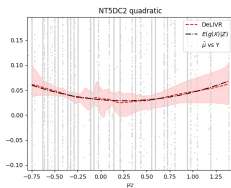
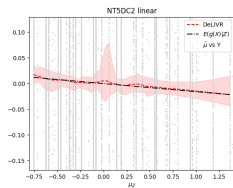
Discussion

- ▶ Alternative: DeLIVR (He et al 2023, Biostatistics).
- ▶ Several new IV deep learning methods...
- ▶ An application: causal feature extraction (Yao et al 2023, Stat in Med).

DeLIVR

- ▶ Stage 2 model: $E(Y|Z) = E[g(X)|Z]$
Problem: estimating $g(X)$.
- ▶ **Key:** $E[g(X)|Z] = h(\mu_Z) \neq g(\mu_Z)$, $\mu_Z = E(X|Z)$.
- ▶ New: estimating $E[g(X)|Z] = h(\mu_Z)$,
Assuming $X|Z \sim N(\mu_Z, \sigma^2)$.
- ▶ Would this address the original Q?
Proposition. Suppose $X|Z \sim N(\mu_Z, \sigma^2)$, and $g(X)$ is a univariate function in X (and independent of μ_Z), then
 1. $g(X) = c$, a constant, if and only if $E(g(X)|Z) = c$.
 2. $g(X)$ is linear in X if and only if $E(g(X)|Z)$ is linear in μ_Z .
 3. $g(X)$ is a k -th degree polynomial in X if and only if $E(g(X)|Z)$ is a k -th degree polynomial in μ_Z .
- ▶ More generally, if $g(X)$ is locally smooth, by a Taylor expansion, ...
- ▶ DeLIVR: estimating an ANN $h_\theta(\cdot)$ for $h(\cdot)$.
- ▶ Inference: use independent training and inference subsamples

Simulation results: DeLIVR more stable than DeepIV



From MRI to AD prediction

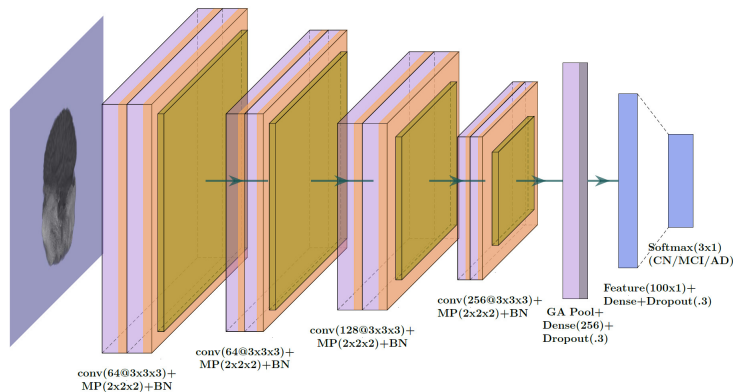


Figure: CNN.

DeepFEIVR

- ▶ Deep Feature Extraction via IV Regression (DeepFEIVR).
- ▶ X : image; Z : SNPs/IVs; Y : AD status.
- ▶ Model:

$$f(X) = ZB + U + \epsilon_X, \quad Y = f(X)\beta + U + \epsilon_Y$$

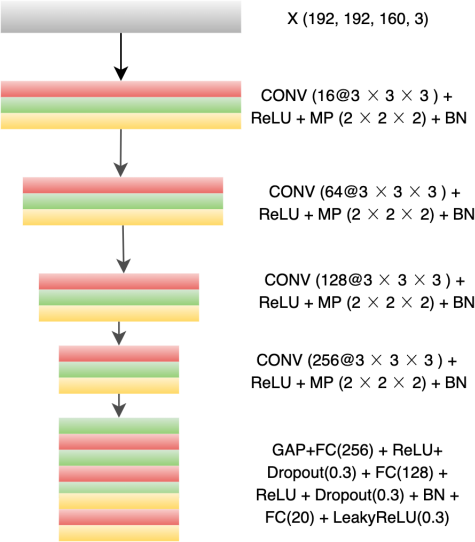
- ▶ Key H_0 : $\beta = 0$.
- ▶ Key challenge: **hidden** confounder U
- ▶ 2SLS-like:

$$\hat{f}(X) = Z\hat{B}, \quad Y = \hat{f}(X)\beta + \epsilon_Y = Z\hat{B}\beta + \epsilon_Y$$

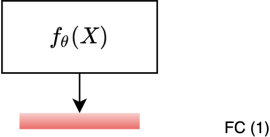
- ▶ Contrast to existing nonparametric IV, e.g. deepIV and DeLIVR:

$$X = ZB + U + \epsilon_X, \quad Y = f(X) + U + \epsilon_Y$$

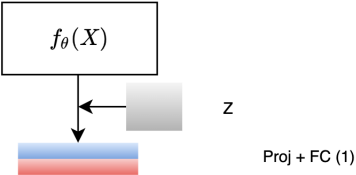
Network architectures



f_θ



(a) a direct CNN model



(b) DeepFEIVR

Second part: No (hidden) confounding

- ▶ Data: $D = \{(X_1, T_1, Y_1), \dots, (X_n, T_n, Y_n)\}$. $T_i = 0$ or 1 .
Goal: any trt effects?
- ▶ **Counterfactual** model:
 $Y_i(1)$ and $Y_i(0)$ are the responses if individual i is and is not given the treatment, respectively.
But we can NOT observe both $Y_i(1)$ and $Y_i(0)$!
- ▶ Unconfoundedness: $T_i \perp (Y_i(1), Y_i(0)) | X_i$
- ▶ individual treatment effect (ITE):

$$\begin{aligned}\tau(x) &:= E[Y_i(1) | X_i = x] - E[Y_i(0) | X_i = x] \\ &= E[Y_i(1) | T_i = 1, X_i = x] - E[Y_i(0) | T_i = 0, X_i = x] \\ &= E[Y_i | T_i = 1, X_i = x] - E[Y_i | T_i = 0, X_i = x],\end{aligned}$$

- ▶ average treatment effect (ATE):
 $\tau := E[Y_i(1) - Y_i(0)] = E[\tau(X)]$.
Note: $E[\bar{Y}(T = 1) - \bar{Y}(T = 0)] \neq \tau$ in general; why?

Standard approaches

- ▶ Old(?) approach: regression!

$$E[Y|T = t, X = x] = t\theta + x'\beta,$$

which can be fitted using data

$$D = \{(X_i, T_i, Y_i) : i = 1, \dots, n\}.$$

Why reasonable? no hidden confounding!

- ▶ But it requires ... especially for high-dim data.
- ▶ Most popular alternative: Propensity Scores (PS)
 $PS(X_i) := Pr(T_i = 1|X_i).$
- ▶ Rosenbaum and Rubin (1983, Biometrika):
 $T_i \perp (Y_i(1), Y_i(0)) | PS(X_i).$
- ▶ Using (X_i, T_i) 's to fit

$$\text{Logit}(Pr(T = 1|X)) = X'\alpha,$$

$$\implies e_i := PS(X_i) = \text{Logit}^{-1}(X_i'\hat{\alpha}).$$

- ▶ Often trim out observations with too small or too large e_i (i.e. outliers).

PS

- ▶ PS regression: fit

$$E[Y|T = t, X = x] = t\theta + PS(x)\gamma$$

using data D .

- ▶ PS matching:
matching each obs with $T_i = 1$ with one (or more) with $T_i = 0$ by their e_i 's, then analysis on matched sets.
- ▶ PS stratification:
partitioning the data into subsets/strata based on the distribution of e_i 's, then stratified analysis.
- ▶ Inverse probability weighting:
each obs is assigned a weight $w_i = 1/e_i$ if $T_i = 1$;
 $w_i = 1/(1 - e_i)$ if $T_i = 0$; then a weighted analysis, e.g.

$$\hat{\tau} = \bar{Y}_w(T = 1) - \bar{Y}_w(T = 0) = \frac{\sum_{i:T_i=1} w_i Y_i}{\sum_{i:T_i=1} w_i} - \frac{\sum_{i:T_i=0} w_i Y_i}{\sum_{i:T_i=0} w_i}.$$

- ▶ But ...

New approaches

- ▶ Dorie et al (2019). Automated versus Do-It-Yourself Methods for Causal Inference: Lessons Learned from a Data Analysis Competition. *Stat Sci*.
- ▶ Simulated data; no hidden confounders,..., as for PS. Standard ones: both PS and (regression) mean response modeled by GLMs; how about by ML?
- ▶ Five competition winners:
 - ▶ BART;
 - ▶ Superlearner + Targeted MLE: ensemble of glm, gbm, gam, glmnet and splines;
 - ▶ calCause: RF or GP by CV;
 - ▶ h2o.ai: ensemble of glm, RF, DL (NN), LASSO and ridge reg;
 - ▶ GBM + MDIA.

Counterfactual RF

- ▶ Lu et al (2018). Estimating Individual Treatment Effect in **Observational** Data Using Random Forest Methods. *JCGS*.
- ▶ M1: C-RF: build two RFs, $\hat{f}_1(X)$ and $\hat{f}_0(X)$, using the subsamples of $T_i = 1$ and $T_i = 0$ respectively; then for each $X_i = x \in D$, run

$$\hat{\tau}(x) = \hat{f}_1(x) - \hat{f}_0(x).$$

better to use the OOB estimate...

- ▶ Or, M2: $\hat{\tau}(x) = RF(x, 1) - RF(x, 0)$, where $RF(X, T)$ is built using all data (X_i, T_i, Y_i) 's.

Model/assumption: $Y_i = f(T_i, X_i) + \epsilon_i$,

In contrast to M1: $Y_i = f_t(X_i) + \epsilon_i$ for $T_i = t$.

- ▶ Or, M3: $\hat{\tau}(x) = RF(x, 1) - RF(x, 0)$, where $RF(X, T)$ is built using all data $(X_i, T_i, X_i * T_i, Y_i)$'s.

- ▶ In analogy, in linear reg:

M1: $Y_i = X_i' \beta_0 + \epsilon_i$ for $T_i = 0$; $Y_i = X_i' \beta_1 + \epsilon_i$ for $T_i = 1$.

M2: $Y_i = T_i \theta + X_i' \beta + \epsilon_i$.

M3: $Y_i = T_i \theta + X_i' \beta + (X_i * T_i) \delta + \epsilon_i$.

Causal trees

- ▶ Ref: Athey and Imbens (2016). Recursive partitioning for heterogeneous causal effects. PNAS.
- ▶ Goal: partition the data into different subpopulations each with a (almost) homogeneous treatment effect.
- ▶ Key idea: similar to CART, but do “honest” estimation: using two independent data subsets for partitioning and parameter estimation.
 1. Use an independent D^{est} , instead of D^{tr} , to estimate leaf means;
 2. Modify the splitting (and CV) criterion to have an unbiased MSE estimator for the causal treatment effect; “fundamental problem of causal inference”: the causal effect is not observed.
 3. Account for increasing variance with tree growing.
- ▶ Use another independent sample for inference.
- ▶ Causal forests (Athey and Wager 2019).

Review: CART for regression

- ▶ Y : continuous.
- ▶ Key: 1) determine splitting variables and split points (e.g. $x_j < t_j$); $\implies R_1, R_2, \dots$;
2) determine c_m in each R_m .
- ▶ in 1), use a sequential or greedy search for each j and s : find $x_j < s$ s.t.
 $R_1(j, s) = \{x | x_j < s\}$, $R_2(j, s) = \{x | x_j \geq s\}$,
 $\min_{j,s} [\min_{c_1} \sum_{X_i \in R_1(j,s)} (Y_i - c_1)^2 + \min_{c_2} \sum_{X_i \in R_2(j,s)} (Y_i - c_2)^2]$.
- ▶ in 2), given R_1 and R_2 ,
 $\hat{c}_k = \text{Ave}(Y_i | X_i \in R_k)$ for $k = 1, 2$.
- ▶ Repeat the process on R_1 and R_2 respectively, ...