

# High-dimensional data: LMs and GLMs

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# Linear Model and Least Squares

- ▶ Data:  $(Y_i, X_i)$ ,  $X_i = (X_{i1}, \dots, X_{ip})'$ ,  $i = 1, \dots, n$ .  
 $Y_i$ : continuous
- ▶ LM:  $Y_i = \beta_0 + \sum_{j=1}^p X_{ij}\beta_j + \epsilon_i$ ,  
 $\epsilon_i$ 's iid with  $E(\epsilon_i) = 0$  and  $\text{Var}(\epsilon_i) = \sigma^2$ .
- ▶  $RSS(\beta) = \sum_{i=1}^n (Y_i - \beta_0 - \sum_{j=1}^p X_{ij}\beta_j)^2 = \|Y - X\beta\|_2^2$ .
- ▶ LSE (OLSE):  $\hat{\beta} = \arg \min_{\beta} RSS(\beta) = (X'X)^{-1}X'Y$ .
- ▶ Nice properties: Under true model,  
 $E(\hat{\beta}) = \beta$ ,  
 $\text{Var}(\hat{\beta}) = \sigma^2(X'X)^{-1}$ ,  
 $\hat{\beta} \sim N(\beta, \text{Var}(\hat{\beta}))$ ,  
Gauss-Markov Theorem:  $\hat{\beta}$  has min var among all linear unbiased estimates.

- ▶ Some questions:

$$\hat{\sigma}^2 = RSS(\hat{\beta}) / (n - p - 1).$$

Q: what happens if the denominator is  $n$ ?

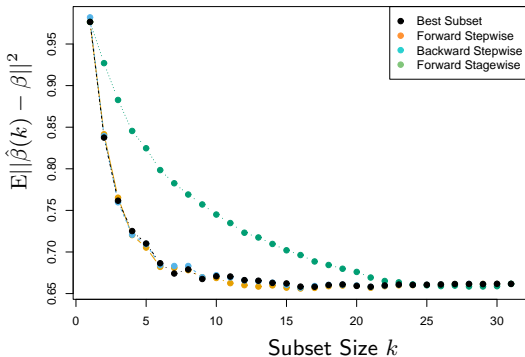
Q: what happens if  $X'X$  is (nearly) singular?

- ▶ What if  $p$  is large relative to  $n$ ?

- ▶ Variable selection:

forward, backward, stepwise: fast, but may miss good ones;

best-subset: too time consuming.



**FIGURE 3.6.** Comparison of four subset-selection techniques on a simulated linear regression problem  $Y = X^T \beta + \varepsilon$ . There are  $N = 300$  observations on  $p = 31$  standard Gaussian variables, with pairwise correlations all equal to 0.85. For 10 of the variables, the coefficients are drawn at random from a  $N(0, 0.4)$  distribution; the rest are zero. □ The noise

# Shrinkage or regularization methods

- ▶ Use regularized or penalized RSS:

$$PRSS(\beta) = RSS(\beta) + \lambda J(\beta).$$

$\lambda$ : penalization parameter to be determined;  
(thinking about the p-value threshold in stepwise selection, or subset size in best-subset selection.)

$J(\cdot)$ : prior; both a loose and a Bayesian interpretations; log prior density.

- ▶ Ridge:  $J(\beta) = \sum_{j=1}^p \beta_j^2$ ; prior:  $\beta_j \sim N(0, \tau^2)$ .

$$\hat{\beta}^R = (X'X + \lambda I)^{-1} X'Y.$$

- ▶ Properties: biased but small variances,

$$E(\hat{\beta}^R) = (X'X + \lambda I)^{-1} X'X\beta,$$

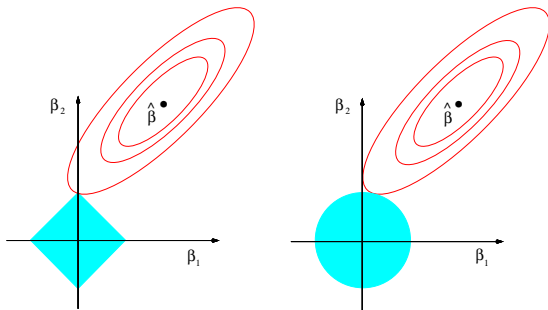
$$\text{Var}(\hat{\beta}^R) = \sigma^2 (X'X + \lambda I)^{-1} X'X (X'X + \lambda I)^{-1} \leq \text{Var}(\hat{\beta}),$$

$$df(\lambda) = \text{tr}[X(X'X + \lambda I)^{-1} X'] \leq df(0) = \text{tr}(X(X'X)^{-1} X') =$$

$$\text{tr}((X'X)^{-1} X'X) = p,$$

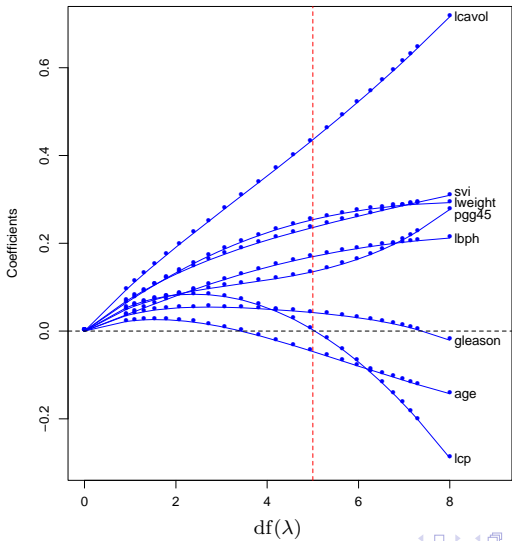
- ▶ Lasso:  $J(\beta) = \sum_{j=1}^p |\beta_j|$ .  
 Prior:  $\beta_j$  Laplace or  $DE(0, \tau^2)$ ;  
 No closed form for  $\hat{\beta}^L$ .
- ▶ Properties: biased but small variances,  
 $df(\hat{\beta}^L) = \#$  of non-zero  $\hat{\beta}_j^L$ 's (Zou et al ).
- ▶ Special case: for  $X'X = I$ , or simple regression ( $p = 1$ ),  
 $\hat{\beta}_j^L = ST(\hat{\beta}_j, \lambda) = \text{sign}(\hat{\beta}_j)(|\hat{\beta}_j| - \lambda)_+$ ,  
 compared to:  
 $\hat{\beta}_j^R = \hat{\beta}_j / (1 + \lambda)$ ,  
 $\hat{\beta}_j^H = HT(\hat{\beta}_j, \lambda) = \hat{\beta}_j I(\hat{\beta}_j > \lambda)$ ,  
 $\hat{\beta}_j^B = HT2(\hat{\beta}_j, M) = \hat{\beta}_j I(\text{rank}(\hat{\beta}_j) \leq M)$ .
- ▶ A key property of Lasso:  $\hat{\beta}_j^L = 0$  for large  $\lambda$ , but not  $\hat{\beta}_j^R$ .  
 –simultaneous parameter estimation and selection.

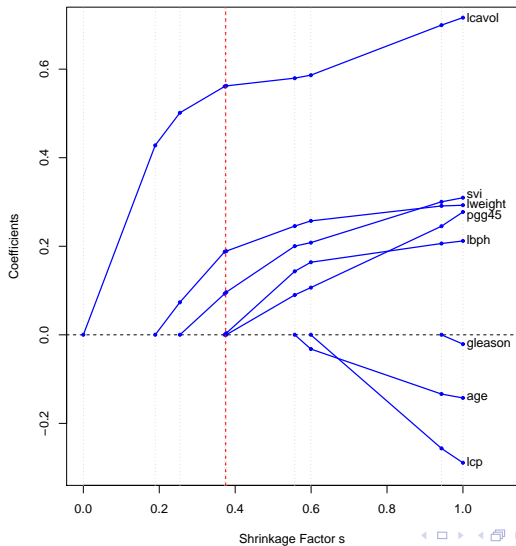
- ▶ Note: for a convex  $J(\beta)$  (as for Lasso and Ridge), min PRSS is equivalent to:  
$$\min RSS(\beta) \text{ s.t. } J(\beta) \leq t.$$
- ▶ Offer an intuitive explanation on why we can have  $\hat{\beta}_j^L = 0$ ; see Fig 3.11.  
Theory:  $|\beta_j|$  is singular at 0; Fan and Li (2001).
- ▶ How to choose  $\lambda$ ?  
obtain a solution path  $\hat{\beta}(\lambda)$ , then, as before, use tuning data or CV or model selection criterion (e.g. AIC or BIC).
- ▶ Least Angle Regression (LARS): fast to find solution paths in LMs.
- ▶ Example: R code ex3.1.r



**FIGURE 3.11.** Estimation picture for the lasso (left) and ridge regression (right). Shown are contours of the error and constraint functions. The solid blue areas are the constraint regions  $|\beta_1| + |\beta_2| \leq t$  and  $\beta_1^2 + \beta_2^2 \leq t^2$ , respectively, while the red ellipses are the contours of the least squares error function.



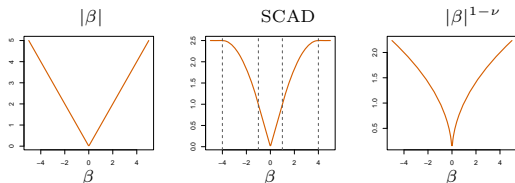




- ▶ Lasso: biased estimates; alternatives:
- ▶ Relaxed lasso: 1) use Lasso for VS; 2) then use LSE or MLE on the selected model.
- ▶ Use a non-convex penalty:
  - SCAD: eq (3.82) on p.92;
  - Bridge  $J(\beta) = \sum_j |\beta_j|^q$  with  $0 < q < 1$ ;
  - Adaptive Lasso (Zou 2006):  $J(\beta) = \sum_j |\beta_j|/|\tilde{\beta}_{j,0}|$ ;
  - Truncated Lasso Penalty (Shen, Pan & Zhu 2012, JASA):
  - TLP( $\beta; \tau$ ) =  $\sum_j \min(|\beta_j|, \tau)$ , or
  - TLP( $\beta; \tau$ ) =  $\sum_j \min(|\beta_j|/\tau, 1) \rightarrow I(\beta \neq 0)$  as  $\tau \rightarrow 0^+$ .
  - MCP: ...
- ▶ Choice b/w Lasso and Ridge: bet on a sparse model? risk prediction for GWAS (Austin, Pan & Shen 2013, *SADM*).
- ▶ Elastic net (Zou & Hastie 2005):

$$J(\beta) = \sum_j \alpha |\beta_j| + (1 - \alpha) \beta_j^2$$

may select more (correlated)  $X_j$ 's.



**FIGURE 3.20.** *The lasso and two alternative non-convex penalties designed to penalize large coefficients less. For SCAD we use  $\lambda = 1$  and  $a = 4$ , and  $\nu = \frac{1}{2}$  in the last panel.*

- ▶ **Group Lasso**: a group of variables  $\beta_{(g)} = (\beta_{j_1}, \dots, \beta_{j_{p_g}})'$  are to be 0 (or not) at the same time,

$$J(\beta) = \sum_g \sqrt{p_g} \|\beta_{(g)}\|_2$$

$L_2$ -norm; not  $L_1$ /Lasso or **squared**  $L_2$ /Ridge.

better in VS (but worse for parameter estimation?)

- ▶ Group SCAD:  $J(\beta) = \sum_g \sqrt{p_g} \text{SCAD}(\|\beta_{(g)}\|_2)$
- ▶ Group TLP:  $J(\beta, \tau) = \sum_g \sqrt{p_g} \text{TLP}(\|\beta_{(g)}\|_2; \tau)$
- ▶ Sparse Group Lasso:  $J(\beta) = (1 - \alpha) \sum_g \sqrt{p_g} \|\beta_{(g)}\|_2 + \alpha \|\beta\|_1$
- ▶ **Grouping**/fusion penalties: encouraging equalities b/w  $\beta_j$ 's (or  $|\beta_j|$ 's).
  - ▶ Fused Lasso:  $J(\beta) = \sum_{j=1}^{p-1} |\beta_j - \beta_{j+1}|$   
 $J(\beta) = \sum_{(j,k) \in G} |\beta_j - \beta_k|$
  - ▶ Generalized Lasso:  $J(\beta) = \|D\beta\|_1$
  - ▶ Grouping pursuit (Shen & Huang 2010, JASA):

$$J(\beta; \tau) = \sum_{j=1}^{p-1} \text{TLP}(\beta_j - \beta_{j+1}; \tau)$$

- ▶ Grouping penalties:
  - ▶ Zhu, Shen & Pan (2013, JASA):

$$J_2(\beta; \tau) = \sum_{j=1}^{p-1} TLP(|\beta_j| - |\beta_{j+1}|; \tau);$$

$$J(\beta; \tau_1, \tau_2) = \sum_{j=1}^p TLP(\beta_j; \tau_1) + J_2(\beta; \tau_2);$$

- ▶ Kim, Pan & Shen (2013, Biometrics):

$$J'_2(\beta) = \sum_{j \sim k} |I(\beta_j \neq 0) - I(\beta_k \neq 0)|;$$

$$J_2(\beta; \tau) = \sum_{j \sim k} |TLP(\beta_j; \tau) - TLP(\beta_k; \tau)|;$$

- ▶ Dantzig Selector (§3.8).
- ▶ Theory (§3.8.5); Greenshtein & Ritov (2004) (persistence); Zou 2006 (non-consistency) ...

## Logistic regression

- ▶ Binary or multinomial logit model: for  $k = 1, \dots, K - 1$ ,

$$\log \frac{Pr(k|x)}{Pr(K|x)} = \beta_{0,k} + x' \beta_{1,k},$$

or equivalently,

$$Pr(k|x) = \frac{\exp(\beta_{0,k} + x' \beta_{1,k})}{1 + \sum_{l=1}^{K-1} \exp(\beta_{0,l} + x' \beta_{1,l})}.$$

Then  $\hat{G}(x) = \arg \max_k Pr(k|x)$ .

- ▶  $x$  can be expanded to include high-order terms.
- ▶ Parameter estimation: MLE  
Note: approx equivalent to fitting multiple binary logit models separately (Begg & Gray, 1984, Biometrika).
- ▶ Logistic reg vs L/QDA: the former is more general; the latter has a stronger assumption and thus possibly more efficient if ...; Logistic reg is quite good.
- ▶ Example code: ex4.1.r

## Penalized logistic regression (§18.3.2, 18.4)

- ▶ Need VS or regularization for a large  $p$ .
- ▶ Add a penalty term  $J(\beta)$  to  $-\log L$   
 $J(\beta)$  can be Lasso, ..., as before.
- ▶ Computing algorithms: a Taylor expansion (i.e. quadratic approx) of  $\log L$ , then the same as penalized LR.
- ▶ R package `glmnet`: an elastic net penalty.  
hence do either Lasso or Ridge (or both).



## R packages for penalized GLMs (and Cox PHM)

- ▶ `glmnet`: Ridge, Lasso and Elastic net.
- ▶ `ncvreg`: SCAD, MCP.
- ▶ `glmtp`: TLP.
- ▶ `grpreg`: group Lasso, group SCAD, ...
- ▶ `seagull`, `SGL`: sparse group Lasso.
- ▶ `genlasso`: generalized Lasso for LMs, including fused Lasso.
- ▶ `FGSG`: grouping/fusion penalties (based on Lasso, TLP, etc) for LMs
- ▶ More general convex programming: `CVXR`; like `CVX`, `CVXPY`.
- ▶ Example 3.3.R

# Computational Algorithms

- ▶ Quadratic programming: the original for Lasso; slow.
- ▶ LARS (§3.8): the solution path is piece-wise linear; at a cost of fitting several single LMs; not general?
- ▶ Incremental Forward Stagewise Regression (§3.8): approx; related to boosting.
- ▶ A simple (and general) way:  $|\beta_j| = \beta_j^2 / |\hat{\beta}_j^{(r)}|$ ;  
truncate a current estimate  $|\hat{\beta}_j^{(r)}| \approx 0$  at a small  $\epsilon$ .
- ▶ Coordinate-descent algorithm (§3.8.6): update each  $\beta_j$  while fixing others at the current estimates—recall we have a closed-form solution for a single  $\beta_j$ !  
simple and general but not applicable to grouping penalties.
- ▶ ADMM (Boyd et al 2011).  
<http://stanford.edu/~boyd/admm.html>
- ▶ For TLP: iterating b/w Difference of Convex (DC) (or MM alg.) and (weighted) lasso

# Inference

- ▶ Q: How to get a p-value or CI for a predictor?  
Challenges: biased estimates; selection bias
- ▶ Sample splitting (to two parts): 1. using the training data for (Lasso) penalized reg (for VS); 2. using the validation data to fit the selected model for inference by OLSE or MLE.  
Refs: Wasserman & Roeder (2009, AoS); Meinshausen, Meier & Bühlmann (2009, JASA).  
+: simple; more general.  
-: loss of efficiency. Better with repeated/multiple splitting.  
R package: `hdi`, function `multi.split()` or `hdi()`.
- ▶ Debiased/de-sparsified lasso (or lasso projection): next page.  
R package: `hdi`, function `lasso.proj()`.
- ▶ Ref: Dezeure et al (2015, *Stat Sci*).  
<https://arxiv.org/pdf/1408.4026.pdf>  
Example: `ex3.4.R`

## Lasso projection

- ▶ Model:  $Y = X\beta + \epsilon$ ,  $X = (X^{(1)}, X^{(2)}, \dots, X^{(p)})$
- ▶ Fact 1:  $\beta_j \neq b_j$  unless ...  
working model:  $Y = X^{(j)}b_j + e$
- ▶ Fact 2: LSEs  $\hat{\beta}_j = \hat{b}_j$  if  $p < n$  AND  
 $Y = Z^{(j)}b_j + e$ ,  $Z^{(j)}$  is a residual vector of regressing  $X^{(j)}$  on all other  $X^{(k)}$ 's with  $k \neq j$ .

Why?  $Z^{(j)} \perp X^{(k)}$

$$\hat{b}_j = (Z^{(j)})'Y / (Z^{(j)})'Z^{(j)} = (Z^{(j)})'Y / (Z^{(j)})'X^{(j)}.$$

$$E(\hat{b}_j) = \beta_j + \sum_{k \neq j} P_{jk}\beta_k, \quad P_{jk} = (Z^{(j)})'X^{(k)} / (Z^{(j)})'X^{(j)}.$$

$$P_{jk} = 0.$$

- ▶ For  $p > n$ , use Lasso to get  $Z^{(j)}$ , then  $P_{jk} \neq 0$ .

$$\hat{\beta}_{C,j} = \hat{b}_j - \sum_{k \neq j} P_{jk}\hat{\beta}_k,$$

$\hat{\beta}$ : Lasso estimates.

$$\hat{\beta}_{C,j} \sim N(0, v_j).$$

# Inference

- ▶ TLP/SCAD: if interested in  $\beta_j$  (that can be high-d for TLP),
  1. use the whole sample to fit a penalized reg model by penalizing all parameters **except**  $\beta_j$ ;
  2. apply the usual Wald or LRT to get the p-value or CI for  $\beta_j$ .Refs: Zhu, Shen & Pan (2020, JASA); Shi et al (2019, AoS).
- ▶ Model-X Knockoffs: FDR control for VS.  
R package: `knockoff`.  
<https://web.stanford.edu/group/candes/knockoffs/index.html>
- ▶ Conformal inference: can give prediction intervals; ...  
R package: <https://github.com/ryantibs/conformal>

# Sure Independence Screening (SIS)

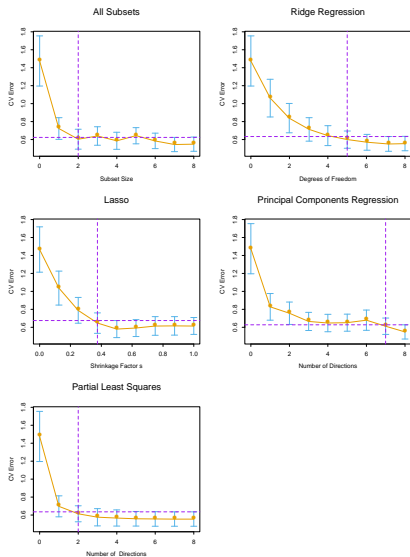
- ▶ Q: penalized (or stepwise ...) regression can do automatic VS; just do it?
- ▶ Key: there is a cost/limit in performance/speed/theory.
- ▶ Q2: some methods (e.g. LDA/QDA/RDA) do not have VS, then what?
- ▶ Going back to basics: first conduct VS in marginal analysis,
  - 1)  $Y \sim X_1, Y \sim X_2, \dots, Y \sim X_p$ ;
  - 2) choose a few top ones, say  $p_1$ ;  
 $p_1$  can be chosen somewhat arbitrarily, or treated as a tuning parameter
  - 3) then apply penalized reg (or other VS) to the selected  $p_1$  variables.
- ▶ Called SIS with theory (Fan & Lv, 2008, JRSS-B).  
R package SIS;  
iterative SIS (ISIS); why? a limitation of SIS ...

## Using Derived Input Directions

- ▶ PCR: PCA on  $X$ , then use the first few PCs as predictors.  
Use a few top PCs explaining a majority (e.g. 85% or 95%) of total variance;  
# of components: a tuning parameter; use (genuine) CV;  
Used in genetic association studies, even for  $p < n$  to improve power.  
+: simple;  
-: PCs may not be related to  $Y$ .

- ▶ Partial least squares (PLS): multiple versions; see Alg 3.3.  
Main idea:
  - 1) regress  $Y$  on each  $X_j$  univariately to obtain coef est  $\phi_{1j}$ ;
  - 2) first component is  $Z_1 = \sum_j \phi_{1j} X_j$ ;
  - 3) regress  $X_j$  on  $Z_1$  and use the residuals as new  $X_j$ ;
  - 4) repeat the above process to obtain  $Z_2, \dots$ ;
  - 5) Regress  $Y$  on  $Z_1, Z_2, \dots$
- ▶ Choice of # components: tuning data or CV (or AIC/BIC?)
- ▶ Contrast PCR and PLS:
  - PCA:  $\max_{\alpha} \text{Var}(X\alpha)$  s.t. ....;
  - PLS:  $\max_{\alpha} \text{Cov}(Y, X\alpha)$  s.t. ....;
  - Continuum regression (Stone & Brooks 1990, JRSS-B)
- ▶ Penalized PCA (...) and Penalized PLS (Huang et al 2004, BI; Chun & Keles 2012, JRSS-B; R packages ppls, spls).
- ▶ Example code: ex3.2.r





**FIGURE 3.7.** Estimated prediction error curves and their standard errors for the various selection and